Variational Mixture of HyperGenerators for Learning Distributions over Functions

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Deep Generative Models

• Learning **probability distributions** on data using Deep Neural Networks.



Generative Adversarial Networks (GANs [1])



Variational Autoencoders (VAEs [2]) Denoising Diffusion Probabilistic Models (DDPMs [3]) Score-based models [4] Energy-based models [5]



Discretization of data

• We typically deal with discretized versions of data that are continuous in nature.



NNs to exploit discretized data



• DNNs are tailored to the data nature.



Real data is continuous in nature



• What if we approximate the underlying **continuous functions**?

 $f : \mathbb{R}^3 \to \{0, 1\}, f(x_1, x_2, x_3) = p$











 $f: \mathbb{R}^2 \to \mathbb{R}^3, f(x_1, x_2) = (r, g, b)$

 $f: \mathbb{R}^2 \to \mathbb{R}, f(\varphi, \lambda) = T$

Real data is continuous in nature



• Learning the distribution of a function allows for **naturally handling**:



Inpainting



Outpainting



Conditional generation



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\\ Super-resolution
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- We can use the same neural architecture independently of the data nature.
- Information to store will be independent of the data size.

• INRs [10-12] can approximate these functions.

How to efficiently learn unique INRs per datapoint?

DGM that generate weights!







$$oldsymbol{X}^{(i)} = \left\{oldsymbol{x}_{d}^{(i)}
ight\}_{d=1}^{D}$$

. D

$$oldsymbol{Y}^{(i)} = \left\{oldsymbol{y}_{d}^{(i)}
ight\}_{d=1}^{D}$$



• Every set of weights and biases, θ_i , comes from a reduced latent representation \boldsymbol{z} .





 $oldsymbol{Y}^{(i)} = \left\{oldsymbol{y}_{d}^{(i)}
ight\}_{d=1}^{D}$

• A hypernetwork [13] converts **z** into weights and biases.



• To learn the parameters of our model, we opt by using **Amortized** Variational Inference, and optimize the following ELBO.

 $\max_{\phi,\psi,\gamma} \mathcal{L}(\phi,\psi,\gamma;\boldsymbol{Y},\boldsymbol{X}) = \max_{\phi,\gamma} \mathbb{E}_{q_{\gamma}(\boldsymbol{z}|\boldsymbol{Y},\boldsymbol{X})} \left[\log p_{\boldsymbol{\theta}}(\boldsymbol{Y}|\boldsymbol{X},\boldsymbol{z}) \right] - D_{KL} \left(q_{\gamma}\left(\boldsymbol{z}|\boldsymbol{Y},\boldsymbol{X}\right) \| p_{\psi}\left(\boldsymbol{z}\right) \right)$





• We incorporate a **Mixture of HyperGenerators** for increased flexibility.

$$\mathcal{L}(\boldsymbol{Y},\boldsymbol{X};\boldsymbol{\psi},\boldsymbol{\phi},\boldsymbol{\gamma}) = \sum_{d=1}^{D} \mathbb{E}_{q_{\gamma_{z}}(\boldsymbol{z}|\boldsymbol{Y},\boldsymbol{X})} \left[\sum_{k=1}^{K} \log p_{\theta_{k}}(\boldsymbol{y}_{d} \mid \boldsymbol{x}_{d}) \cdot \pi_{dk} \right] - D_{KL}(q_{\gamma_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{z}}(\boldsymbol{z}))$$

$$- D_{KL}(q_{\gamma_{c}}(\boldsymbol{C} \mid \boldsymbol{z},\boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{c}}(\boldsymbol{C} \mid \boldsymbol{z},\boldsymbol{X}))$$

$$- D_{KL}(q_{\gamma_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{z}}(\boldsymbol{z}))$$

$$- D_{K}(q_{\gamma_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{z}}(\boldsymbol{z}) || p_{\psi_{z}}(\boldsymbol{z})$$

$$- D_{K}(q_{\gamma_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{z}}(\boldsymbol{z}) || p_{\psi_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y})|| p_{\psi_{z}}(\boldsymbol{z})$$

$$- D_{K}(q_{\gamma_{z}}(\boldsymbol{z} \mid \boldsymbol{X},\boldsymbol{Y}) || p_{\psi_{z}}(\boldsymbol{z}) || p_{\psi_$$



• We incorporate a **Mixture of HyperGenerators** for increased flexibility.



Image Reconstruction with Mixture of HyperGenerators



 $p(\boldsymbol{z}) \qquad q(\boldsymbol{z}|\boldsymbol{X}_i,\boldsymbol{Y}_i)$

• To alleviate the **holes** problem, similarly like Latent Diffusion models [15], we learn the prior as a planar Flow [16].







• We achieve **comparable sampling quality** and diversity wrt baselines.



			CelebA HQ			Shapes3D		
	Model \downarrow FID \uparrow Precision \uparrow		↑ Recall	\downarrow FID	↑ Precision	↑ Recall		
S DeepMind	[17] [18]	GASP (Dupont et al., 2022b)	$\textbf{14.01} \pm \textbf{0.18}$	$\textbf{0.81} \pm \textbf{0.0}$	$\textbf{0.43} \pm \textbf{0.01}$	118.66 ± 0.64	0.01 ± 0.0	0.16 ± 0.01
		Functa (Dupont et al., 2022a)	40.40	-	-	57.81 ± 0.15	0.06 ± 0.0	0.13 ± 0.0
		VaMoH	66.27 ± 0.18	0.65 ± 0.0	0.0 ± 0.0	$\textbf{56.25} \pm \textbf{0.57}$	$\textbf{0.08} \pm \textbf{0.0}$	$\textbf{0.64} \pm \textbf{0.01}$



(b) POLYMNIST

• We naturally generate samples with **any desired resolution**.



(b) POLYMNIST



• Our method allows for **efficient conditional generation via inference**.



(b) Missing half of the image



• Our method allows for **efficient conditional generation via inference**.





• We achieve a 7-11 times faster inference than the alternative!

	Model	Inference T	ïme (secs)	Speed Improvement		
Dataset	VaMoH	Functa (3)	Functa (10)	vs. Functa (3)	vs. Functa (10)	
POLYMNIST	0.00453	0.01648	0.05108	x 3.64	x 11.28	
Shapes3D	0.00536	0.01759	0.05480	x 3.28	x 10.22	
CELEBA HQ	0.00757	0.01733	0.05381	x 2.29	x 7.11	
ERA5	0.00745	0.01899	0.05932	x 2.55	x 7.96	
ShapeNet	0.00689	0.02095	0.06576	x 3.04	x 9.54	



Conclusion

- Thanks to **learning distributions of functions**, our proposed **VAMoH** can:
 - "Sample" neural networks for generating new data.
 - **Infer** the la**tent representation** of a neural network for conditionally generating data.
 - Use the same neural architecture independently of the nature of the data.
 - Easily perform the **conditional generation at any desired resolution**, while being:
 - \checkmark Robust to partially observed data.
 - ✓ **Expressive** for generating high-quality data.
 - ✓ Efficient in terms of inference.





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